

# Ruchservomotor Ltd.

BY-220019, Montazhnikov 5, Minsk, Republic of Belarus  
 Tel: +375(17) 254-04-43; Fax: +375(17) 254-04-48  
 email: info@ruchservomotor.com  
 http://www.ruchservomotor.com

\_\_\_\_\_ . \_\_\_\_\_ 2011

## Page of enquiry / order № \_\_\_\_\_

Firm / position:	<input type="text"/>	business card
Contact person:	<input type="text"/>	
Tel / fax:	<input type="text"/>	
Address:	<input type="text"/>	
E-mail:	<input type="text"/>	

### Type of drive

Rotary Step Motor RRM	<input type="checkbox"/>	Linear Motor in ALU profile LSMA-T-____	<input type="checkbox"/>
Planar (dual-axis) Step Motor PRM	<input type="checkbox"/>	Rotary Synchronous Motor RM-____	<input type="checkbox"/>
Linear Synchronous Motor LSM-____	<input type="checkbox"/>	Cross-table /3 coordinates machine	<input type="checkbox"/>
Linear Synchronous Symmetry Motor LSSM-____	<input type="checkbox"/>	Gantry System (Portal)	<input type="checkbox"/>
Linear Synchronous Iron-Less Motors LSIM-____	<input type="checkbox"/>	Laser Cut _____ - ____	<input type="checkbox"/>
	<input type="checkbox"/>		<input type="checkbox"/>
	<input type="checkbox"/>		<input type="checkbox"/>

Quantity of coordinates: _____		X	Y	Z	C
Required movement	mm( <sup>0</sup> )				
Payload	kg(kg.m <sup>2</sup> )				
Holding force (moment)	N (Nm)				
Positioning accuracy in statics	micron(")				
Positioning accuracy in dynamics	micron(")				
Resolution/Repeatability					
Maximal velocity	m/s(rpm)				
Maximal acceleration	m/s <sup>2</sup>				

### Movement

point-to-point   
 trajectory movement(contour)

### interface of control system:

RS232   
 Step/Dir   
 ±10V   
 Other

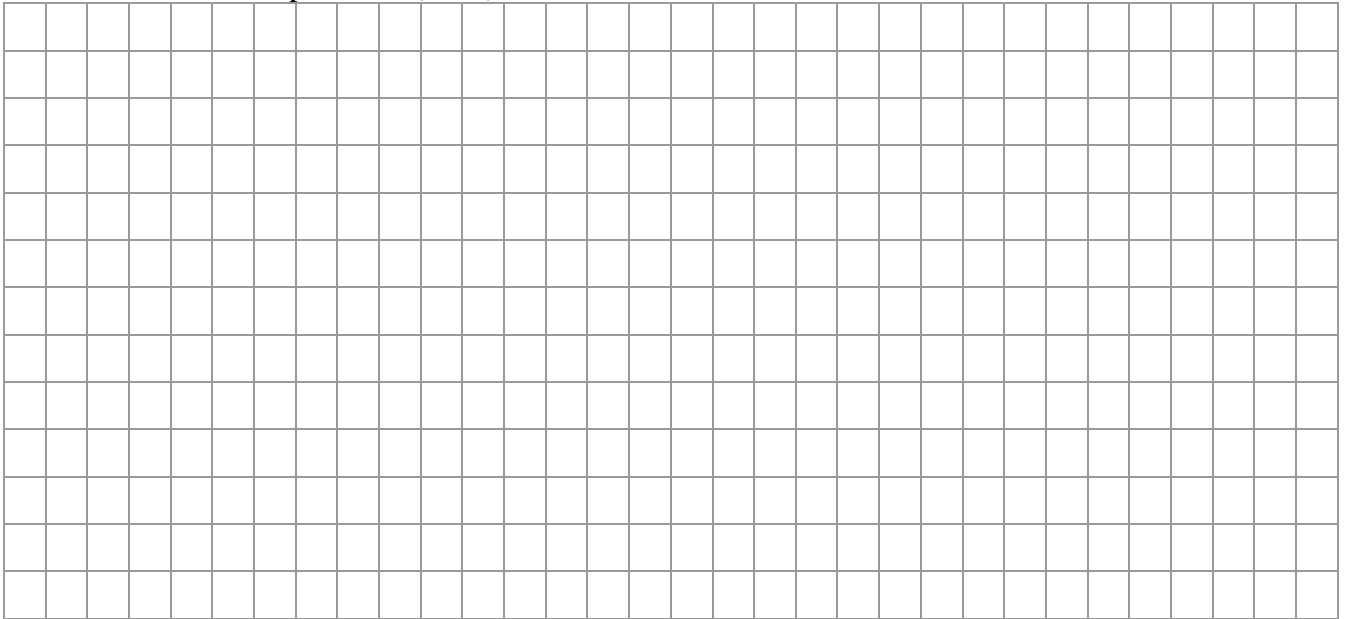
### Status:

interest	<input type="checkbox"/>	catalogue	<input type="checkbox"/>	required q-ty pcs./yea	<input type="checkbox"/>
customer	<input type="checkbox"/>	offer	<input type="checkbox"/>		<input type="checkbox"/>
second contact	<input type="checkbox"/>	contract	<input type="checkbox"/>		<input type="checkbox"/>

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Thank for information. We hope for successful cooperation.

Positional relationship of axes (load ) of the user



The graph of speed / time



Description of a duty cycle (distance, traveling time, stopping time... ..)

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Additional information:

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Additional requirement:

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Thank for information. We hope for successful cooperation.